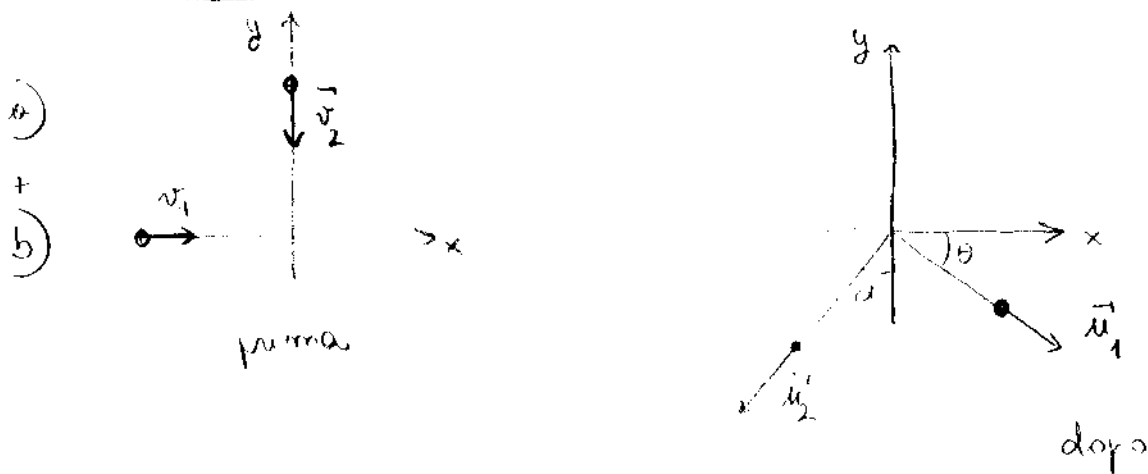


Problema 1



cons. della q d moto

$$m_1 \vec{v}_1 + m_2 \vec{v}_2 = m_1 \vec{u}_1 + m_2 \vec{u}_2$$

Urto elastico $\Rightarrow$ cons. dell'energia meccanica

$$\frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 = \frac{1}{2} m_1 u_1^2 + \frac{1}{2} m_2 u_2^2$$

So che $m_1 = m_2 = m$

$$\vec{v}_1 = v_1 \hat{x}$$

$$\vec{v}_2 = -v_2 \hat{y}$$

$$\vec{u}_1 = u_1 \cos \theta \hat{x} - u_1 \sin \theta \hat{y}$$

$$\vec{u}_2 = -u_2 \sin \alpha \hat{x} - u_2 \cos \alpha \hat{y}$$

$\Rightarrow$ riscrivere le eq. come:

$$\begin{cases} m v_1 \hat{x} - m v_2 \hat{y} = m (u_1 \cos \theta \hat{x} - u_1 \sin \theta \hat{y}) + m (-u_2 \sin \alpha \hat{x} - u_2 \cos \alpha \hat{y}) \\ \frac{1}{2} m v_1^2 + \frac{1}{2} m v_2^2 = \frac{1}{2} m u_1^2 + \frac{1}{2} m u_2^2 \end{cases} \Rightarrow$$

$$\begin{cases} v_1 = u_1 \cos \theta - u_2 \sin \alpha \\ -v_2 = -u_1 \sin \theta - u_2 \cos \alpha \\ v_1^2 + v_2^2 = u_1^2 + u_2^2 \end{cases}$$

$$\begin{cases} u_2 \sin \alpha = u_1 \cos \theta - v_1 \\ u_2 \cos \alpha = v_2 - u_1 \sin \theta \end{cases} \Rightarrow u_2^2 = u_1^2 + v_1^2 - 2v_1 u_1 \cos \theta + v_2^2 - 2v_2 u_1 \sin \theta$$

$$\cancel{v_1^2} + \cancel{v_2^2} = \cancel{u_1^2} + u_1^2 + \cancel{v_1^2} + \cancel{v_2^2} - 2v_1 u_1 \cos \theta - 2v_2 u_1 \sin \theta$$

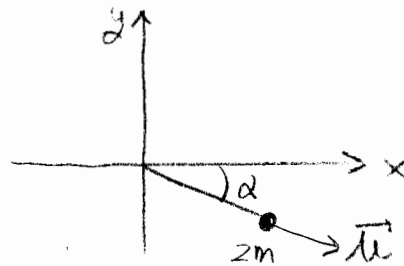
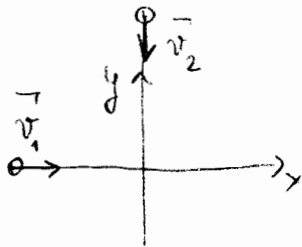
$$2u_1 (u_1 - v_1 \cos \theta - v_2 \sin \theta) = 0$$

$$u_1 = v_1 \cos \theta + v_2 \sin \theta$$

$$\tan \alpha = \frac{v_1 \cos^2 \theta + v_2 \sin \theta \cos \theta - v_1}{v_2 - v_1 \cos \theta \sin \theta - v_2 \sin^2 \theta} = \frac{-v_1 \sin^2 \theta + v_2 \sin \theta \cos \theta}{v_2 \cos^2 \theta - v_1 \cos \theta \sin \theta}$$

$$= \tan \theta \frac{\cancel{v_2 \cos \theta} - \cancel{v_1 \sin \theta}}{\cancel{v_2 \cos \theta} - \cancel{v_1 \sin \theta}} = \tan \theta \Rightarrow \alpha = \theta$$

c)
d)



Altro modo:

$$v_1^2 + v_2^2 = u_1^2 + u_2^2$$

$$\vec{v}_1 + \vec{v}_2 = \vec{u}_1 + \vec{u}_2 = 0$$

$$v_1^2 + v_2^2 + 2v_1 v_2 \cos 90^\circ = 0$$

$$\underbrace{u_1^2 + u_2^2}_{v_1^2 + v_2^2} + 2u_1 u_2 \cos \theta_{12} = 0$$

$$\Rightarrow 2u_1 u_2 \cos \theta_{12} = 0$$

$$\theta_{12} = 90^\circ = \alpha + 90^\circ - \theta \Rightarrow \alpha = \theta$$

cons. delle q. di moto ($\vec{u}_1 = \vec{u}_2 = \vec{u}$)

$$m v_1 \hat{x} - m v_2 \hat{y} = 2m u (\cos \alpha \hat{x} - \sin \alpha \hat{y})$$

$$\Rightarrow m v_1 = 2m u \cos \alpha$$

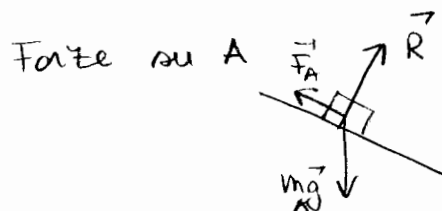
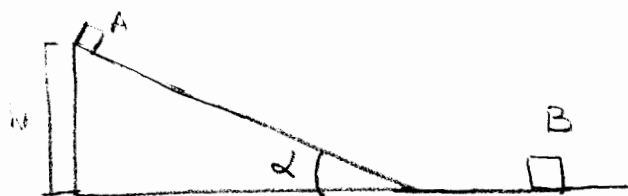
$$m v_2 = 2m u \sin \alpha$$

$$\tan \alpha = \frac{v_2}{v_1}$$

$$4u^2 = v_1^2 + v_2^2 \Rightarrow$$

$$u = \frac{\sqrt{v_1^2 + v_2^2}}{2}$$

Problema 2



a) T F V $\Rightarrow E_{\text{cin},A}(f) - E_{\text{cin},A}(i) = L_{\text{peso}} + L_R + L_{F_{\text{att}}}$

$$L_{\text{peso}} = mgh$$

$$L_R = 0$$

ipotenusa triangolo $\Rightarrow l = \frac{h}{\sin \alpha}$

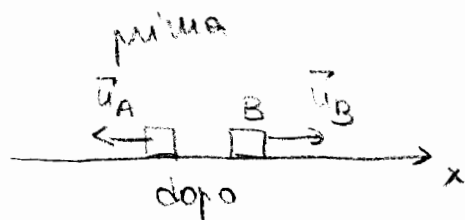
$$L_{F_{\text{att}}} = -\mu_D R l = -\mu_D mg \cos \alpha \frac{h}{\sin \alpha}$$

$R = mg \cos \alpha$

$$\Rightarrow \frac{1}{2} m_A v_A^2 - 0 = m_A g h - m_A \mu_D g \cos \alpha \frac{h}{\sin \alpha}$$

$$v_A = \sqrt{2gh \left(1 - \frac{\mu_D}{\tan \alpha}\right)}$$

b)



C. della q.d. moto $\begin{cases} m_A v_A = -m_A u_A + m_B u_B \\ \text{conserv. in cinetica} \end{cases}$

$$\begin{cases} m_A v_A^2 = \frac{1}{2} m_A u_A^2 + \frac{1}{2} m_B u_B^2 \end{cases}$$

$$\Rightarrow u_A = \frac{m_B u_B - m_A v_A}{m_A} \Rightarrow$$

$$m_A v_A^2 = \frac{m_A}{m_A^2} (m_B^2 u_B^2 + m_A^2 v_A^2 - 2 m_A m_B u_B v_A) + m_B u_B^2$$

$$\cancel{u_A} v_A^2 = \cancel{u_A} \frac{m_B^2}{m_A^2} m_B^2 + \cancel{v_A^2} m_A^2 - 2 m_B m_B v_A + m_B u_B^2$$

$$\cancel{u_B} \left(1 + \frac{m_B}{m_A}\right) u_B^2 - 2 \cancel{u_B} v_A \cancel{u_B} = 0$$

$$u_B = \frac{2 v_A m_A}{m_A + m_B}$$

$$c) u_A = \left[m_B \left(\frac{2 v_A m_A}{m_A + m_B} \right) - m_A v_A \right] \frac{1}{m_A}$$

$$= \frac{\cancel{2} m_A m_B v_A - m_A^2 v_A - \cancel{m_A m_B v_A}}{m_A (m_A + m_B)}$$

$$= \frac{\cancel{m_A} v_A}{\cancel{m_A}} \frac{m_B - m_A}{m_A + m_B}$$

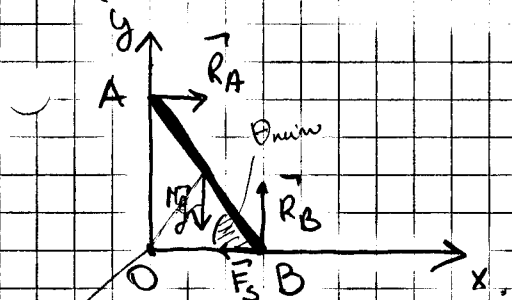
$$TFV \quad + \frac{1}{2} \cancel{u_A} u_A^2 = + \cancel{u_A} g h' + \mu_D \cancel{u_A} g \cos \frac{h'}{\sin \alpha}$$

$$h' = \frac{u_A^2}{2g} \frac{1}{\left(1 + \frac{\mu_D}{\tan \alpha}\right)} = \frac{(m_B - m_A)^2}{(m_A + m_B)^2} \frac{2g h'}{\cancel{2g}} \frac{\left(1 - \frac{\mu_D}{\tan \alpha}\right)}{\left(1 + \frac{\mu_D}{\tan \alpha}\right)}$$

$$= h' \frac{(m_B - m_A)^2}{(m_A + m_B)^2} \frac{\tan \alpha - \mu_D}{\tan \alpha + \mu_D}$$

(Esercizio della scala) Problema 3

A5



$\theta_{\min}$ t.c. scala non cade?

$$1) \quad \sum \vec{F}^E = 0 \rightarrow \vec{R}_A + \vec{R}_B + \vec{Mg} + \vec{F}_S = 0$$

$$2) \quad \sum \vec{M}_O^E = 0$$

$$\begin{cases} R_A - F_S = 0 \\ -Mg + R_B = 0 \end{cases} \rightarrow \begin{cases} F_S = R_A \\ R_B = Mg \end{cases}$$

$$- R_A \cancel{l} \sin \theta + R_B \cancel{l} \cos \theta - Mg \cancel{\frac{l}{2}} \sin \left(\frac{\pi}{2} - \theta \right) = 0$$

$$- \frac{1}{2} Mg \cos \theta + R_B \cos \theta - R_A \sin \theta = 0$$

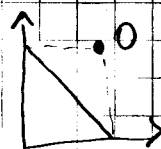
$$- \cancel{\frac{1}{2} Mg \cos \theta} + \underset{\wedge}{\frac{1}{2} Mg \cos \theta} - F_S \sin \theta = 0$$

$$F_S = \frac{1}{2} Mg \frac{1}{\tan \theta} \leq \mu_s R_B = \mu_s Mg$$

$$\Rightarrow \frac{1}{2} \frac{1}{\tan \theta} \leq \mu_s \quad \tan \theta \geq \frac{1}{2\mu_s}$$

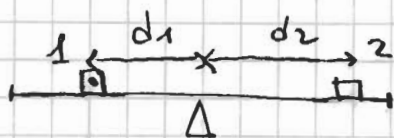
$$\Rightarrow \tan \theta_{\min} = \frac{1}{2\mu_s}$$

Assai più facile se per O si sceglieva

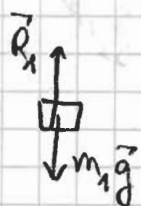


Problema 4

6



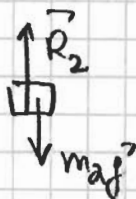
Forze su 1:



$$1 \text{ in eq} \Rightarrow \vec{R}_1 + m_1 \vec{g} = 0$$

$$\vec{R}_1 = -m_1 \vec{g}$$

Analogamente per 2:

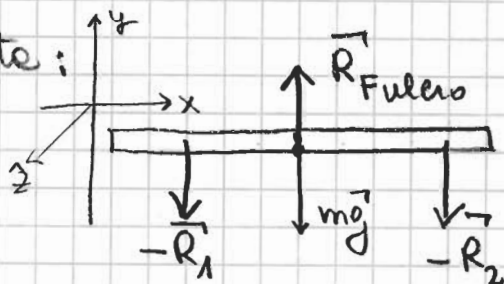


$$2 \text{ in eq} \Rightarrow \vec{R}_2 + m_2 \vec{g} = 0$$

$$\vec{R}_2 = -m_2 \vec{g}$$

Se $\vec{R}_1$ è esercitata dall'asta sul bambino 1, per il 3° principio, il bambino 1 esercita sull'asta la forza $-\vec{R}_1$. Analogamente per 2. $\Rightarrow$

Forze sull'asta:



$$-\vec{R}_1 = m_1 \vec{g}$$

$$-\vec{R}_2 = m_2 \vec{g}$$

$$\text{Asta in eq} \Rightarrow \vec{F}_E = 0$$

$$\vec{M}_{E,0} = 0$$

$$m_1 \vec{g} + m_2 \vec{g} + m \vec{g} + \vec{R}_F = 0$$



non ho informazioni su d_2 ! $\Leftrightarrow R_F = (m_1 + m_2 + m) g$

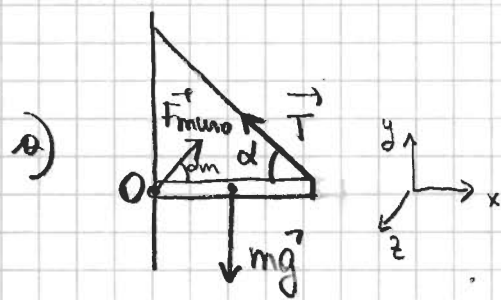
Scelgo 0 nel centro di massa $\Rightarrow \vec{M}_{mg} = 0, \vec{M}_{R_F} = 0$

$$\Rightarrow m_1 g d_1 \hat{z} - m_2 g d_2 \hat{z} = 0$$

$$\Rightarrow d_2 = \frac{m_1}{m_2} d_1$$

Problema 5

7



$$\text{Eq} \Rightarrow \vec{F}_{\text{muro}} + \vec{T} + m\vec{g} = 0 \quad \vec{F}_E = 0$$

$$-mg \cancel{\frac{1}{2}} \hat{z} + \hat{z} T \cancel{\frac{1}{2}} \sin \alpha = 0 \quad \vec{M}_E = 0$$

$$\Rightarrow T = \frac{mg}{2 \sin \alpha}$$

b)

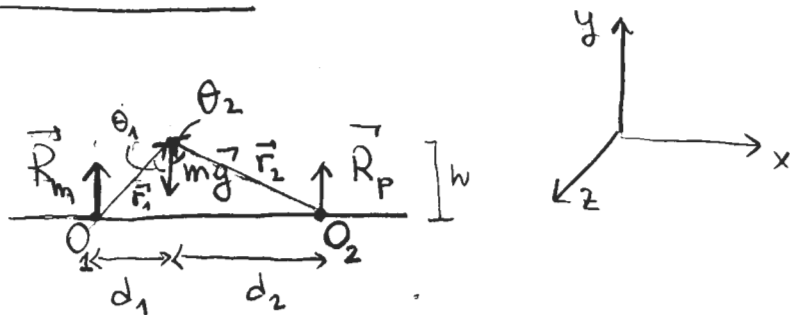
$$\begin{cases} F_{mx} - \frac{mg}{2 \sin \alpha} \cos \alpha = 0 & F_{mx} = \frac{mg}{2 \sin \alpha} \cos \alpha \\ F_{my} + \frac{mg}{2 \sin \alpha} \sin \alpha - mg = 0 & F_{my} = \frac{mg}{2} \end{cases}$$

$$\Rightarrow F_m = \sqrt{F_{mx}^2 + F_{my}^2} = \frac{mg}{2 \sin \alpha} = T$$

$$\tan \alpha_m = \frac{F_{my}}{F_{mx}} = \frac{\frac{mg}{2}}{\frac{mg \cos \alpha}{2 \sin \alpha}} = \tan \alpha \Rightarrow$$

$$\alpha_m = \alpha$$

Problema 6



(a) Calcolo $\vec{M}_{O,E} = 0$ e per polo O scelgo O_2

$$\Rightarrow R_m (d_1 + d_2) (-\hat{z}) + mg \underbrace{d_2 \sin \theta_2}_{d_2} \hat{z} = 0$$

$$R_m (d_1 + d_2) = mg d_2$$

$$R_m = mg \frac{d_2}{d_1 + d_2}$$

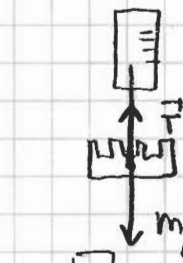
(b) Calcolo $\vec{M}_{O,E} = 0$ con polo in O_1

$$R_p (d_1 + d_2) \hat{z} - mg \underbrace{d_1 \sin \theta_1}_{d_1} \hat{z} = 0$$

$$R_p = mg \frac{d_1}{d_1 + d_2}$$

Problema 7

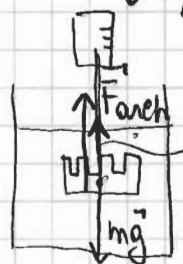
Nell'aria



$T =$ quello che misura la bilancia

$$T = p = mg$$

Nell'acqua



$$T = Pa = -Farch + mg =$$

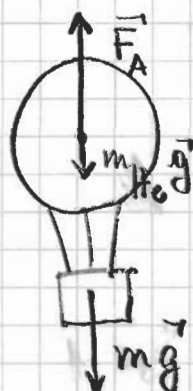
$$= -\rho_{H_2O} V g + \rho_{canoa} V g$$

$$\frac{Pa}{mg} = \frac{Pa}{P} = \frac{\rho_{canoa} - \rho_{H_2O}}{\rho_{canoa}}$$

$$\rho_c \frac{Pa}{P} = \rho_c - \rho_{H_2O}$$

$$\rho_c = \frac{\rho_{H_2O}}{1 - \frac{Pa}{P}} = \rho_{H_2O} \frac{mg}{(mg - Pa)}$$

Problema 8



$$F_A = (m_{He} + m) g$$

$$F_A = V \rho_a g$$

$$\Rightarrow \rho_a V g = \rho_{He} V g + mg$$

$$V = \frac{m}{\rho_a - \rho_{He}} = 421 \text{ m}^3$$

Nota ad h maggiori

ρ_{canoa} diminuisce

$\Rightarrow V$ ancora + grande