

Introduction to Pressure-Anisotropy-Driven Instabilities.

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Lectures for the SWIFF School, Spineto 6-7 June 2012

Reading:
MNRAS 405, 291
(2010) and
refs therein

S1. Kinetic Description of a Magnetised Plasma.

In order to start having an adequate theoretical understanding of the primary topic of these lectures, it is necessary first to gain a good mastery of the general kinetic framework in which dynamics of magnetised plasma is studied. I will spend quite a large fraction of time allotted for these lectures on this extended introduction because it involves material that is not generally part of standard plasma courses - although it provides a natural connection between fluid descriptions (MHD, etc.) and the fully kinetic ones.

Our goal is to develop a theoretical framework for plasmas that are strongly magnetised and weakly collisional in the sense that

$$\gamma_{ie}, \gamma_{ii}, \gamma_{ei}, \gamma_{ee} \ll \Omega_i, \Omega_e \\ \text{collision frequencies} \quad \text{Larmor frequencies}$$

$$\text{or } \rho_i, \rho_e \ll \lambda_{mfp} \\ \text{Larmor radius} \quad \text{mean free path}$$

We will also mostly consider low-frequency dynamics,
 $\omega \ll \Omega_i, \Omega_e$

and (less generally) long wavelengths : $k\rho_i, k\rho_e \ll 1$.

-2- 1.1 Kinetic Equation

Let us start from "the beginning":

the Vlasov - Landau - Maxwell system of equations:

distribution function $f_s(t, \vec{r}, \vec{v})$ of species $s (=e, i)$

satisfies

Vlasov

$$\frac{\partial f_s}{\partial t} + \vec{v} \cdot \nabla f_s + \frac{e_s}{m_s} \left(\vec{E} + \frac{\vec{v} \times \vec{B}}{c} \right) \cdot \frac{\partial \vec{v}}{\partial t} = \left(\frac{\partial f_s}{\partial t} \right)_c \quad (1)$$

streaming Lorentz force collisions

Landau

$$\begin{aligned} \nabla \cdot \vec{E} &= 4\pi \sum_s e_s n_s, \quad n_s = \int d^3 \vec{v} f_s \\ \nabla \cdot \vec{B} &= 0 \\ \frac{\partial \vec{B}}{\partial t} &= -c \nabla \times \vec{E} \end{aligned}$$

$$\vec{J} = \sum_s e_s n_s \vec{u}_s, \quad \vec{u}_s = \frac{1}{n_s} \int d^3 \vec{v} \vec{v} f_s$$

Maxwell

$$\begin{aligned} \nabla \times \vec{B} &= \frac{4\pi}{c} \vec{J} + \text{magnetic induction} \\ &\sim k^2 \lambda_{De}^2 \ll 1 \end{aligned}$$

neglected for wavelength

$\gg \lambda_{De}$ - quasi-neutrality

because

$$\frac{kE}{4\pi e \delta n} \sim \frac{k^2 \varphi}{4\pi e \delta n} \sim \frac{k^2 T}{4\pi e^2 n} \sim \frac{k^2 m_e v_{the}^2}{4\pi e^2 n} \sim \frac{k^2 v_{the}^2}{c^2 \omega_{pe}^2}$$

$$\frac{1}{c} \frac{\partial E}{\partial t} \sim \frac{\omega^2 / k^2}{c^2} \ll 1$$

displacement current reflected when non-relat.

because

$$\frac{\frac{1}{c} \omega E}{k B} \sim \frac{\frac{1}{c^2} \omega^2 \frac{1}{k} B}{k B} \sim \frac{\omega^2}{k^2 c^2}$$

Our intuition likes imagining plasmas as a fluid, with some density $n_s = \int d^3 \vec{v} f_s$

and velocity $\vec{u}_s = \frac{1}{n_s} \int d^3 \vec{v} \vec{v} f_s$

(and perhaps pressure, temperature or some generalization thereof). This is rooted in the fact that gases we are used to (e.g. our atmosphere) are very

collisional, so ~~then~~ the $(\frac{\partial f}{\partial t})_c$ term dominates ($\nu \gg \omega$) and so to lowest order the distribution function is a local Maxwellian:

$$f_s = \frac{n_s}{(4\pi V_{th_s}^2)^{3/2}} e^{-\frac{(\vec{v} - \vec{u}_s)^2}{V_{th_s}^2}}, \quad V_{th_s} = \sqrt{\frac{2T_s}{m_s}}$$

as then all we need to do is derive equations for u_s , \bar{u}_s , T_s and also sometimes for perturbations of the particle distribution function and f_s (to calculate transport coefficients: viscosity, thermal diffusivity etc.)

Here we will be concerned with a situation in which collisions are not quite so dominant ($\nu \sim \omega$ or $\ll \omega$). How do we generalise this fluid approach then?

Let's first make a minor preliminary step, namely, change variables

$$\vec{v} \rightarrow \vec{w} = \vec{v} - \vec{u}_s(t, \vec{r}) \text{ peculiar velocity}$$

where $\vec{u}_s = \frac{1}{n_s} \int d^3 \vec{v} \vec{v} f_s$ the exact mean flow velocity.

So our particle kinetics will always be relative to the mean flow of the plasma.

$$(\frac{\partial}{\partial t})_{\vec{v}} = (\frac{\partial}{\partial t})_{\vec{w}} + (\frac{\partial \vec{w}}{\partial t})_{\vec{v}} \cdot \frac{\partial}{\partial \vec{w}} = \frac{\partial}{\partial t} - \frac{\partial \vec{u}_s}{\partial t} \cdot \frac{\partial}{\partial \vec{w}}$$

$$(\nabla)_{\vec{v}} = (\nabla)_{\vec{w}} + (\nabla \vec{w})_{\vec{v}} \cdot \frac{\partial}{\partial \vec{w}} = \nabla - (\nabla \vec{u}_s) \cdot \frac{\partial}{\partial \vec{w}}$$

$$\text{so } \vec{v} \cdot \nabla \rightarrow \vec{u}_s \cdot \nabla - (\vec{u}_s \cdot \nabla \vec{u}_s) \cdot \frac{\partial}{\partial \vec{w}} + \vec{w} \cdot \nabla - (\vec{w} \cdot \nabla \vec{u}_s) \cdot \frac{\partial}{\partial \vec{w}}$$

Let $\frac{d}{dt} = \frac{\partial}{\partial t} + \vec{u}_s \cdot \nabla$ convective derivative for species s

Then the kinetic equation becomes

$$\boxed{\frac{df_s}{dt} + \vec{w} \cdot \nabla f_s + \left(\frac{e_s}{m_s} \frac{\vec{w} \times \vec{B}}{c} + \vec{a}_s - \vec{w} \cdot \nabla \vec{u}_s \right) \cdot \frac{\partial f_s}{\partial \vec{w}} = \left(\frac{\partial f_s}{\partial t} \right)_c} \quad (2)$$

where $\vec{a}_s = \frac{e_s}{m_s} \left(\frac{\vec{u}_s \times \vec{B}}{c} + \frac{d\vec{u}_s}{dt} \right)$ acceleration (independent of \vec{w} !)

To this we must now attach Maxwell's equations:

$$\sum_s e_s n_s = 0 \quad \text{quasineutrality} \quad (3)$$

$$\frac{\partial \vec{B}}{\partial t} = -c \nabla \times \vec{E} \quad \text{Faraday} \quad (4)$$

$$\nabla \times \vec{B} = \frac{4\pi}{c} \vec{j} = \frac{4\pi}{c} \sum_s e_s n_s \vec{u}_s \quad \text{Ampère} \quad (5)$$

and the constraint $\int d^3 \vec{w} \vec{w} f_s = 0$, which can be thought of as implicitly determining \vec{u}_s .

We are now going to spin out a fluid-like description for our plasma with these equations as the starting point.

1.2 Moment Equations

Take moments of (2) : NB use $\int d^3 \vec{w} \vec{w} f_s = 0$!

$$\int d^3 \vec{w} (2) : \frac{d n_s}{dt} + (\nabla \cdot \vec{u}_s) n_s = 0$$

↑ from ① ↑ from ⑤ after integration by parts

$$NB: \int d^3 \vec{w} \left(\frac{\partial f_s}{\partial t} \right)_c = 0 \quad \text{conservation of particles}$$

This is the continuity equation:

$$\boxed{\frac{\partial n_s}{\partial t} + \nabla \cdot (\vec{u}_s n_s) = 0} \quad (6)$$

$$\int d^3 \vec{w} m_s \vec{w} (2) : \nabla \cdot \left(\int d^3 \vec{w} m_s \vec{w} f_s - \vec{a}_s n_s m_s \right) = \vec{R}_s$$

↑ particle momentum (relative to mean flow) ↑ from ② ↑ from ④ ↑ from ⑥
 ↓ ↓ ↓ ↓
 \hat{P}_s pressure tensor

interspecies friction force

$$\vec{R}_s = \int d^3 \vec{w} m_s \vec{u} \left(\frac{\partial f_s}{\partial t} \right)_c$$

This is the momentum equation:

$$\boxed{m_s n_s \frac{d \vec{u}_s}{dt} = -\nabla \cdot \hat{P}_s + e_s n_s \left(\vec{E} + \vec{u}_s \times \vec{B} \right) + \vec{R}_s} \quad (7)$$

We are interested in mass flow (momentum) \dot{m}_e ,

so we add (7)_i + (7)_e and use

$$m_e \vec{u}_e + m_i \vec{u}_i \approx m_i \vec{u}_i \equiv m_i \vec{u} \quad (m_i \gg m_e)$$

$$\hat{P} = \sum_s \hat{P}_s, \quad \sum_s \vec{R}_s = 0 \quad (\text{momentum conservation})$$

$$\sum_s e_s n_s = 0 \quad (\text{quasineutrality}) \quad (\text{by elastic collision})$$

$$\therefore \sum_s e_s n_s \vec{u}_s = \vec{J} = \frac{e}{4\pi} \nabla \times \vec{B} \quad (\text{Ampère})$$

This gives

$$\boxed{m_i n_i \frac{d\vec{u}}{dt} = -\nabla \cdot \hat{\vec{P}} + \frac{(\nabla \times \vec{B}) \times \vec{B}}{4\pi}} \quad (8)$$

$$\text{where } \frac{d}{dt} = \frac{\partial}{\partial t} + \vec{u} \cdot \nabla$$

Lorentz force

The rhs can be written in a nice divergence form:

$$\boxed{m_i n_i \frac{d\vec{u}}{dt} = -\nabla \cdot \left(\hat{\vec{P}} + \underbrace{\frac{1}{8\pi} \frac{\vec{B}^2}{8\pi} - \frac{\vec{B}\vec{B}}{4\pi}}_{\text{Maxwell stress}} \right)} \quad (9)$$

all the kinetic physics is
in this tensor!

So, we have equations for n_i and \vec{u} , but still need to calculate \vec{B} and $\hat{\vec{P}}$.

We'll deal with \vec{B} first, which is easier, as then discern $\hat{\vec{P}}$ at great length as this is where all the interesting (for the purposes of these lectures) physics is contained.

1.3. Magnetic Field.

Faraday: $\frac{\partial \vec{B}}{\partial t} = -c \nabla \times \vec{E}$ (4)

So we need to calculate \vec{E} . Note we do this not from Poisson eqn (where $\nabla \cdot \vec{E}$ is small as $k^2 \lambda_{de}^{-2}$)
 a) so \vec{E} is not explicitly present), but from the electron momentumless equation, (7)_e, which is also known as the "generalised Ohm's law":

$$\vec{E} + \frac{\vec{u}_e \times \vec{B}}{c} = \frac{\vec{R}_e}{en_e} - \frac{\nabla \cdot \hat{P}_e}{en_e} - \cancel{\frac{me}{e} \frac{d\vec{v}_e}{dt}}$$

↓
 e. field in the frame of the ch. fluid
 ↓
 friction
 ↓
 resistivity
 = \vec{j}/σ

 ↑
 "electron thermal force"
 ("thermoelectric term")

 ↑
 electron inertia
 small because $me \ll M_i$
 $\frac{me \omega_e}{ue B/c} \sim \frac{\omega}{5k_B} \ll 1$

Since $en_e(\vec{u}_i - \vec{u}_e) = \vec{j}$
 this is
 $\frac{\vec{u}_e \times \vec{B}}{c} - \frac{\vec{j} \times \vec{B}}{cen_e}$ ← "Hall term"

Because $\vec{R}_e = -\nu e i m_e n_e (\vec{u}_e - \vec{u}_i) =$
 $= \frac{\nu e i m_e}{e} \vec{j}$
 So $\frac{1}{\sigma} = \frac{\nu e i m_e}{e^2 n_e}$

So,
$$\vec{E} = -\frac{\vec{u}_e \times \vec{B}}{c} + \cancel{\frac{\vec{j}}{\sigma}} - \frac{\vec{j} \times \vec{B}}{cen_e} - \frac{\nabla \cdot \hat{P}_e}{en_e}$$
 (10)

Since $\vec{j} = \frac{c}{4\pi} \nabla \times \vec{B}$, everything here is expressed in terms of \vec{u}, \vec{B} or $n_e (= \frac{e_i}{e} n_i \equiv Z n_i)$ except \hat{P}_e , which we have not yet discussed.

Substitute (10) into (4) :

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B}) + \eta \Delta \vec{B} + c \nabla \times \left[\frac{(\nabla \times \vec{B}) \times \vec{B}}{4\pi e n_e} + \frac{\nabla \cdot \hat{P}_e}{e n_e} \right]$$

usual MHD "induction
equation"

$$\eta = \frac{c^2}{4\pi\sigma} = \frac{c v_{ei} m_e}{4\pi e^2 n_e} \quad (ii)$$

$= v_{ei} d_e^2$ mag. diffusivity
(small when coll's are small)

It is useful to know that the Hall or thermoelectric terms are only important at short spatial scales.

Hall:

$$\frac{c k^2 B^2 / 4\pi e n_e}{\omega B} \sim \frac{c^2 m_i}{4\pi e^2 n_i} \frac{k^2}{\omega} \frac{eB}{m_i c} \sim k^2 d_i^2 \frac{\Omega_i}{\omega}$$

$$\frac{\eta k^2 B}{\omega B} \sim \frac{v_{ei} k^2 d_e^2}{\omega} \ll 1$$

$$\text{If } \omega \sim k v_A \sim \frac{k B}{\sqrt{4\pi n_i m_i}}, \text{ then } \frac{\omega}{\Omega_i} \sim \frac{k B m_i c}{\sqrt{4\pi n_i m_i} e B} \sim k d_i,$$

so Hall term $\sim k d_i \ll 1$ as long as we stay above the ion inertial scale.

Thermoelectric:

$$\frac{c k^2 v_{the} m_e n_e / e n_e}{\omega B} \sim \frac{k^2 v_{the}^2 / m_i c}{\omega e B} \sim k^2 p_i^2 \frac{\Omega_i}{\omega} \sim$$

$$\sim k p_i \frac{p_i}{d_i} \sim k p_i \sqrt{\beta_i} \text{ where } \beta_i = \frac{n_i T_i}{B^2 / 8\pi}, T_i = \frac{m_i v_{thi}^2}{2}$$

$\sim \frac{k d_i}{\sqrt{\beta_i}}$ small as long as we stay above the ion inertial and ion Larmor scales.

(for now, let $\beta_i \approx 1$).

1.4 Gyrotropic Plasmas.

Now let us tackle the pressure tensor

$$\hat{P}_s = \int d^3\vec{w} m_s \vec{w} \vec{w} f_s$$

In general, in order to know what it is, we still need to solve the kinetic equation (2), so despite all the work we have done so far, no real simplification has yet been achieved.

Note that term (3) in eq.(2) can be written as:

$$\frac{e_s}{m_s} \frac{\vec{w} \times \vec{B}}{c} \cdot \frac{\partial f_s}{\partial \vec{w}} = -\Omega_s \left(\frac{\partial f_s}{\partial \vartheta} \right)_{w_\perp, w_\parallel}$$

where $\Omega_s = \frac{e_s B}{m_s c}$ is the Larmor frequency and ϑ is the gyroangle - angle at which the particle orbits the magnetic field.

Ex. Prove this! (just let $w_x = w_\perp \cos \vartheta$, $w_y = w_\perp \sin \vartheta$ etc.
- cylindrical coordinates locally in velocity space) ↴ wrt \vec{B}

So, eq.(2) can be written so:

$$\begin{aligned} \Omega_s \left(\frac{\partial f_s}{\partial \vartheta} \right)_{w_\perp, w_\parallel} &= \frac{d f_s}{dt} + \vec{w} \cdot \nabla f_s + (\vec{a}_s - \vec{w} \cdot \nabla \vec{u}_s) \cdot \frac{\partial f_s}{\partial \vec{w}} - \left(\frac{\partial f_s}{\partial t} \right)_c \quad (2) \\ (3) & \quad (1) \quad (2) \quad (4) \quad (5) \quad (6) \end{aligned}$$

Let us now consider a situation when the lhs is \gg the rhs. Then, to lowest order,

$$\frac{\partial f_s}{\partial \theta} = 0 \quad \omega \approx f_s(t, r, w_{\perp}, w_{\parallel})$$

- The distribution function is gyrotropic, i.e., independent of the gyroangle.

To lowest order in what?

$$\frac{①}{③} \sim \frac{\omega}{\Omega_s} \ll 1 \quad \text{low frequency}$$

$$\sim \frac{k u_s}{\Omega_s} \sim k p_s \frac{u_s}{v_{th,s}} \ll 1 \quad \text{long wavelength}$$

$$\frac{②}{③} \sim \frac{k v_{th,s}}{\Omega_s} \sim k p_s \ll 1 \quad \text{long wavelength}$$

$$\frac{④}{③} \sim \frac{a_s}{\Omega_s v_{th,s}} \sim \frac{\vec{E} + \vec{u}_s \times \vec{B}}{\frac{m_s}{e_s} \Omega_s v_{th,s}} \sim k p_s \quad \begin{array}{l} \text{from gen'l Ohm's law} \\ \text{use } \nabla \cdot \vec{E} / cne \text{ (biggest term)} \\ \cancel{\text{or smaller}} \end{array} \ll 1$$

$$\frac{⑤}{③} \sim \frac{k v_{th,s} u_s}{\Omega_s v_{th,s}} \sim k p_s M_a \ll 1$$

$$\frac{⑥}{③} \sim \frac{v_s}{\Omega_s} \ll 1 \quad \begin{array}{l} \text{weakly collisional} \\ (=magnetized) \end{array} \quad \begin{array}{l} \text{otherwise coll's will} \\ \text{dominate } \omega \text{ } f_s \text{ will} \\ \text{become isotropic} \end{array}$$

Thus, we are safe in this approximation if

$$\omega \ll \Omega_i \quad \text{and} \quad k p_i \ll 1 \quad \text{and} \quad \gamma_i \ll \Omega_i$$

magnetised weakly collisional plasma

For such a plasma, the pressure tensor is greatly simplified:

$$\begin{aligned}
 \hat{P}_s &= \int d^3 \vec{w} \underbrace{\langle \vec{w} \vec{w} \rangle_0}_{\parallel} f_s(t, \vec{r}, w_{\perp}, w_{\parallel}) = \\
 &\quad \frac{w_{\perp}^2}{2} (\mathbb{1} - \vec{B} \vec{B}) + w_{\parallel}^2 \vec{B} \vec{B} \quad \text{where } \vec{B} = \frac{\vec{B}^0}{B} \\
 &= (\mathbb{1} - \vec{B} \vec{B}) \underbrace{\int d^3 \vec{w} m_s \frac{w_{\perp}^2}{2} f_s}_{\text{III}} + \vec{B} \vec{B} \underbrace{\int d^3 \vec{w} m_s w_{\parallel}^2 f_s}_{\text{III}} \\
 &= \left(\begin{array}{c} P_{1s} \\ P_{1s} \\ P_{1s} \end{array} \right) \quad \text{so we simply have two scalar pressures,} \\
 &\quad \text{perp. \& parallel to the}
 \end{aligned}$$

Denote $p_{\perp} = \sum_s p_{\perp s}$ local direction of \vec{B}

∴ $p_{11} = \sum_S p_{11S}$, we get

$$\nabla \cdot \hat{\vec{P}} = \nabla \cdot [(\mathbb{1} - \hat{b}\hat{b}) P_L + \hat{b}\hat{b} P_{\parallel}] = \nabla P_L - \nabla \cdot [\hat{b}\hat{b}(P_L - P_{\parallel})]$$

so the momentum equation is

1.5 Origin of Pressure Anisotropy.

Let us momentarily interrupt the formal flow and ask where pressure anisotropies might come from and how large they are likely to be. This discussion is qualitative as we will subsequently rederive everything more rigorously.

If the magnetic field in a plasma changes sufficiently slowly ~~($\omega \ll \Omega_i$)~~ ($\omega \ll \Omega_i$) ~~so particles don't interact~~, ω particles rarely collide ($v_{ii} \ll \Omega_i$), then each particle has an adiabatic invariant (we'll prove that) (called first adiabatic invariant) $\mu = \frac{m w_{\perp}^2}{2B}$ ($\mu = \text{const directly}$ from eq. (12) later).

Physically, this can be thought of as the magnetic moment of a current loop formed by a gyroorbit or angular momentum of the gyrating particle ($m w_{\perp} r = m w_{\perp} \cdot w_{\perp} / \Omega_i = m w_{\perp}^2 / (eB/mc) \propto m w_{\perp}^2 / B$).

Now the sum of all these μ 's is

$$\int d^3 \vec{w} \mu f = \frac{P_{\perp}}{B} \quad (\text{in fact } N \frac{P_{\perp}}{nB} \text{ density, but let } n = \text{const for now})$$

Let us express this expectation that μ is conserved:

$$\frac{1}{P_{\perp}} \frac{d P_{\perp}}{dt} \sim - \frac{1}{B} \frac{d B}{dt} - \sqrt{\frac{P_{\perp} - P_{\parallel}}{P_{\perp}}} \quad (14)$$

↑ conservation ↑ collisional tendency to isotropize pressure.

non-rigorous at this stage, derivation later.

Thus, we expect that if ambient magnetic field changes in a plasma, this should cause p_{\perp} to change, so as to preserve $p_{\perp} - p_{\parallel}$ — a process possibly attenuated by collisions if they are large enough to compete.

If they indeed are large enough, we can make a simple estimate of the ~~velocities~~ pressure anisotropy:

$$\Delta \equiv \frac{p_{\perp} - p_{\parallel}}{p_{\perp}} \sim \frac{1}{\gamma} \frac{1}{B} \frac{dB}{dt} \sim \frac{\text{rate of change of } B}{\text{coll. rate}} \quad *)$$

Example: solar wind is expanding, B is dropping, expect ~ 1 negative pressure anisotropy at 1 AU

Let us recall the induction equation [Eq. (11)], dropping all the small-scale terms]:

$$\vec{\nabla} \cdot \frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{u} \times \vec{B}) = -\vec{u} \cdot \nabla \vec{B} + \vec{B} \cdot \nabla \vec{u} \quad (\nabla \cdot \vec{u} = 0 \text{ for simplicity, incompressible})$$

$$\frac{1}{B} \frac{dB}{dt} = \vec{B} \cdot (\nabla \vec{u})$$

Thus, $\frac{p_{\perp} - p_{\parallel}}{p_{\perp}} \sim \frac{\vec{B} \cdot (\nabla \vec{u}) \cdot \hat{b}}{\gamma} \leftarrow \text{rate of strain}$

$$\text{or } p_{\perp} - p_{\parallel} \sim \left(\frac{p_{\perp}}{\gamma} \right) \hat{b} \hat{b} : \nabla \vec{u}$$

$$\sim \frac{m_i n_i v_{thi}^2}{\gamma_{ii}} \sim \text{dissipation collisional viscosity}$$

*) ~~Electron~~ Note that this means that the electron pressure anisotropy is usually smaller than the ion one:

$$\Delta_e / \Delta_i \sim \frac{v_{te}}{v_e} \sim \sqrt{\frac{m_e}{m_i}} \ll 1 \quad (\text{as indeed is the case in SW})$$

In eq. (13) we have therefore

$$\nabla \cdot [\vec{b} \vec{b} (p_{\perp} - p_{\parallel})] \sim \nabla \cdot \left[\frac{p_{\perp}}{\nu} \vec{b} \vec{b} \vec{b} : \nabla \vec{u} \right]$$

— precisely the familiar (to some, at least!) parallel (Braginskii) viscosity term [so, in the coll. limit, equations can be closed]

Thus, pressure anisotropy = parallel viscosity, although, as we are going to see shortly, while its effect on large scales is dissipative, at small scales it will be wildly destabilizing.

Intuitively this is because $p_{\perp} \neq p_{\parallel}$ is a non-equilibrium situation and so is a source of free energy, the pressure-anisotropic system will want to relax towards isotropy. It can do so via collisions, of course, but it can (or will) also be impatient with their slippishness and find ways of exciting instabilities, which will then push it towards equilibrium — a common phenomenon.

From eq. (13), we can also estimate under what conditions $p_{\perp} - p_{\parallel}$ is likely to prove an important effect: clearly we must compare it with $B^2/4\pi$

So $\frac{p_{\perp} - p_{\parallel}}{p} \ll \frac{B^2}{4\pi p} \sim \frac{2}{\beta}$ pressure anisotropy irrelevant

$\frac{p_{\perp} - p_{\parallel}}{p} > \frac{2}{\beta}$ pressure anisotropy potentially important.

1.6 Kinetic MHD.

Let us now bring our quest for a fluid system of equations to a kind of completion by working out the evolution equations for p_{\perp} or p_{\parallel} (one of which will be a somewhat corrected form of eq. (14)).

Let us go back to eq. (12). We agreed that to lowest order, $\frac{\partial f_{os}}{\partial \theta} = 0$, so $f_s = f_{os} + \delta f_s$ and

$$\sum_s \frac{\partial \delta f_s}{\partial \theta} = \frac{d f_{os}}{dt} + \vec{w} \cdot \nabla f_{os} + (\vec{a}_s - \vec{w} \cdot \nabla \vec{u}_s) \cdot \frac{\partial f_{os}}{\partial \vec{w}} - \left(\frac{\partial f_{os}}{\partial t} \right)_c \quad (15)$$

We can annihilate the lhs by averaging this equation over gyroangles. Since $f_{os} = f_{os}(t, \vec{r}, w_{\perp}, w_{\parallel})$, the gyroaverage of the rhs will give us a closed equation for the distribution function.

It turns out that mathematically the least cumbersome calculation can be done if we use (w, w_{\parallel}) instead of $(w_{\perp}, w_{\parallel})$ as variables.

↪ $w = w_{\perp}^2 + w_{\parallel}^2$ [they also have the advantage that for isotropic distribution, $\partial f / \partial w_{\parallel} = 0$, so $f = f(t, \vec{r}, w)$]

The time or spatial derivatives in the rhs of (15) must be carefully transformed because our change of variables mixes phase space:

$$(t, \vec{r}, \vec{w}) \rightarrow (t, \vec{r}, w, w_{\parallel}, \vartheta), \text{ where } w_{\parallel} = \vec{w} \cdot \hat{b}(t, \vec{r})$$

$$\text{and } f_{os} = f_{os}(t, \vec{r}, w, w_{\parallel}) \quad [\text{drop subscripts in what follows}]$$

$$\text{NB: } \int d^3 \vec{w} = 2\pi \int_0^\infty dw w \int_{-\pi}^\pi dw_{\parallel}$$

$$\text{Then } \left(\frac{df}{dt} \right)_{\vec{w}} = \left(\frac{df}{dt} \right)_{w, w_{||}} + \left(\frac{dw_{||}}{dt} \right)_{\vec{w}} \left(\frac{\partial f}{\partial w_{||}} \right)_w \\ = \frac{df}{dt} + \frac{d\vec{b}}{dt} \cdot \vec{w} \frac{\partial f}{\partial w_{||}}$$

$$(\nabla f)_{\vec{w}} = (\nabla f)_{w, w_{||}} + (\nabla w_{||})_{\vec{w}} \left(\frac{\partial f}{\partial w_{||}} \right)_w \\ = \nabla f + (\nabla \vec{b}) \cdot \vec{w} \frac{\partial f}{\partial w_{||}}$$

~~Separate cases~~ Also

$$\frac{\partial f}{\partial \vec{w}} = \vec{w} \frac{\partial f}{\partial w} + \vec{b} \frac{\partial f}{\partial w_{||}}.$$

So, the gyroaveraged eqn (15) is

$$\frac{df}{dt} + \frac{d\vec{b}}{dt} \cdot \underbrace{\langle \vec{w} \rangle}_{\vec{w}_{||} \vec{b}} \frac{\partial f}{\partial w_{||}} + \underbrace{\langle \vec{w} \rangle \cdot \nabla f}_{\vec{w}_{||} \vec{b}} + \underbrace{\langle \vec{w} \vec{w} \rangle : (\nabla \vec{b}) \frac{\partial f}{\partial w_{||}}}_{\frac{w_{\perp}^2}{2} (1 - \vec{b} \cdot \vec{b}) + w_{||}^2 \vec{b} \cdot \vec{b}} +$$

because $\vec{b} \cdot \frac{d\vec{b}}{dt} = \frac{1}{2} \frac{d\vec{b}^2}{dt} = 0$

NB: $(\nabla \vec{b}) \cdot \vec{b} = \frac{1}{2} \nabla \vec{b}^2 = 0$

$$+ \vec{a} \cdot \left(\underbrace{\langle \vec{w} \rangle}_{\frac{w_{\perp}^2}{2} \vec{b}} \frac{\partial f}{\partial w} + \vec{b} \frac{\partial f}{\partial w_{||}} \right) - (\nabla \vec{u}) : \underbrace{\langle \vec{w} \vec{w} \rangle}_{\frac{w_{\perp}^2}{2w} (1 - \vec{b} \cdot \vec{b})} \frac{\partial f}{\partial w} - \underbrace{\langle \vec{w} \rangle}_{\vec{w}_{||} \vec{b}} \cdot (\nabla \vec{u}) \cdot \vec{b} \frac{\partial f}{\partial w_{||}} \\ = \left\langle \left(\frac{\partial f}{\partial t} \right)_c \right\rangle$$

$\nabla \cdot \vec{b} = - \frac{\vec{b} \cdot \nabla B}{B}$

$$\frac{df}{dt} + w_{||} \vec{b} \cdot \nabla f + \frac{w_{\perp}^2}{2} (\nabla \cdot \vec{b}) \frac{\partial f}{\partial w_{||}} + \vec{a} \cdot \vec{b} \left(\frac{w_{||}}{w} \frac{\partial f}{\partial w} + \frac{\partial f}{\partial w_{||}} \right)$$

mirrorforce

$$- (\nabla \cdot \vec{u}) \frac{w_{\perp}^2}{2w} \frac{\partial f}{\partial w} + (\vec{b} \cdot \nabla \vec{u}) \left[\left(\frac{w_{\perp}^2}{2} - w_{||}^2 \right) \frac{1}{w} \frac{\partial f}{\partial w} - w_{||} \frac{\partial f}{\partial w_{||}} \right]$$

$$= \left\langle \left(\frac{\partial f}{\partial t} \right)_c \right\rangle$$

(16)

This equation, coupled with the definitions of p_{\perp} & p_{\parallel} , the induction equation (11) (without the small-scale terms) & the momentum equation (13) constitute a closed system, known as "Kinetic MHD".

Note that the continuity eqn (6) is redundant (formally) as it can be obtained from (16) by integrating over velocities. ~~The same is true about the parallel projection of the momentum equation, (13) · \vec{b} , because \vec{a} contains the $\frac{d\vec{u}}{dt}$ term.~~ The same is true about the parallel projection of the momentum equation, (13) · \vec{b} , because \vec{a} contains the $\frac{d\vec{u}}{dt}$ term.

In standard treatments (e.g. Kulsrud's review in the Handbook of Plasma Physics - 1983 or his earlier, more detailed, Varian lecture notes), eq. (16) is written in $(w_{\perp}, w_{\parallel})$ [or sometimes $(w_{\perp}, v_{\parallel})$] variables - or (μ, w_{\parallel}) where $\mu = \frac{m w_{\perp}^2}{2B}$.

In this last form, μ conservation becomes manifest in the sense that the kinetic equation for $f(t, \vec{r}, \mu, w_{\parallel})$ contains no μ derivatives:

$$\frac{df}{dt} + w_{\parallel} \vec{b} \cdot \nabla f - \left(\vec{b} \cdot \frac{d\vec{u}}{dt} + w_{\parallel} \vec{b} \vec{b} : \nabla \vec{u} + \frac{\mu}{m} \vec{b} \cdot \nabla B - \frac{e}{m} E_{\parallel} \right) \frac{\partial f}{\partial w_{\parallel}} = \left(\frac{\partial f}{\partial t} \right)_{\text{mirror force}}$$

(Ex. Derive this by changing variables from eq.(16)) (17)

This is nice as compact, but mixing B into velocity variables introduces some unwelcome complications into practical calculations, so I recommend eq.(16) over this.

The final piece we need to take care of is the parallel electric field contained in

$$\vec{a}_s \cdot \hat{b} = \frac{e_s}{m_s} \vec{E} \cdot \hat{b} - \hat{b} \cdot \frac{d\vec{s}}{dt}$$

[NB btw that all \vec{u} 's are \vec{u}_s 's, so $\vec{u}_c = \vec{u}$ set by (13) and $\vec{u}_e = \vec{u} - \frac{1}{e_n e} \vec{J}$, $\vec{J} = \frac{e}{4\pi} \nabla \times \vec{B}$]

\vec{J} but this term is small compared to \vec{u} if $k d_i \ll 1$

For this we use the generalized Ohm's law (10):

$$\vec{E} \cdot \hat{b} = \frac{1}{\sigma} \vec{J} \cdot \hat{b} - \frac{1}{e_n e} (\nabla \cdot \hat{P}_e) \cdot \hat{b}$$

small:

- $\frac{1}{\sigma} \vec{J} \parallel \sim \frac{vei c K B e_n e}{e^2 n e 4\pi K m_e v_{the}^2 n e}$
- $\frac{1}{e_n e} \nabla_{||} P_{||e} \sim \frac{vei c K B e_n e}{e^2 n e 4\pi K m_e v_{the}^2 n e}$
- $\sim \frac{vei c B}{4\pi e_n e v_{the}^2} \sim$
- $\sim \frac{vei c^2 m_e}{4\pi e^2 n e} \frac{e B}{m_e c} \frac{1}{v_{the}^2}$
- $\sim \frac{vei}{5e} \frac{d\phi}{\rho e^2} \ll 1$

$$\begin{aligned} & \left\{ \nabla \cdot [P_{||e}(1 - \vec{b} \cdot \vec{b}) + P_{\perp e} \vec{b} \cdot \vec{b}] \right\} \cdot \hat{b} = \\ &= \vec{b} \cdot \nabla P_{||e} - \left\{ \nabla \cdot [\vec{b} \cdot \vec{b} (P_{||e} - P_{\perp e})] \right\} \cdot \hat{b} \\ &= \cancel{\vec{b} \cdot \nabla P_{||e}} - (\nabla \cdot \vec{b}) (P_{||e} - P_{\perp e}) \\ &\quad - \vec{b} \cdot \nabla (P_{||e} - P_{\perp e}) = \\ &= \vec{b} \cdot \nabla P_{||e} - (P_{||e} - P_{\perp e}) (\nabla \cdot \vec{b}) \end{aligned}$$

the usual
thermoelectric
term.

$\frac{-\vec{b} \cdot \nabla B}{B}$
from $\nabla \cdot \vec{B} = 0$

small (or can be)

$\frac{P_{||e} - P_{\perp e}}{P_{||e}} \sim \frac{\omega}{v_{ei}} \ll 1$
if electrons are collisional

(assuming $\omega \sim v_{ii} \sim \sqrt{\frac{m_e}{m_i}} v_{ei}$)

$$\boxed{\vec{E} \cdot \hat{b} = - \frac{\vec{b} \cdot \nabla P_{||e}}{e_n e}} \quad (18)$$

$+ (P_{||e} - P_{\perp e}) \frac{\nabla \cdot \hat{b}}{e_n e}$ if we wish to keep the el. anisotropy

NB: The approximations involving the smallness of the m_e/m_i mass ratio are not essential here. Formally speaking, we can keep all those small terms and do the mass-ratio expansion later on, as a subsidiary one.

Let us summarise the equations:

$$\frac{\partial n_i}{\partial t} + \nabla \cdot (n_i \vec{u}) = 0 \quad [\text{superfluous}] \quad (6)$$

$$m_i n_i \frac{d\vec{u}}{dt} = -\nabla (P_{\perp} + \frac{B^2}{8\pi}) + \nabla \cdot [BB(P_{\perp} - P_{\parallel} + \frac{B^2}{4\pi})] \quad (13)$$

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{u} \times \vec{B}) \quad \cancel{+ \mu_0 \epsilon_0 \nabla \cdot \vec{B}} \quad (11)$$

$$P_{\perp} = \sum_s P_{\perp s}, \quad P_{\perp s} = \int d^3 \vec{w} m_s \frac{w_{\perp}^2}{2} f_s$$

$$P_{\parallel} = \sum_s P_{\parallel s}, \quad P_{\parallel s} = \int d^3 \vec{w} m_s w_{\parallel} f_s$$

$$\begin{aligned} \frac{df_s}{dt} + w_{\parallel} \hat{b} \cdot \nabla f_s + \frac{w_{\perp}^2}{2} (\nabla \cdot \hat{b}) \frac{\partial f}{\partial w_{\parallel}} + \left(\frac{e_s}{m_s} E_{\parallel} - \hat{b} \cdot \frac{d\vec{u}}{dt} \right) \left(\frac{w_{\parallel}}{W} \frac{\partial f}{\partial w} + \frac{\partial f}{\partial w_{\parallel}} \right) \\ - (\nabla \cdot \vec{u}) \frac{w_{\perp}^2}{2W} \frac{\partial f}{\partial w} + (BB \cdot \nabla \vec{u}) \left[\left(\frac{w_{\perp}^2}{2} - w_{\parallel}^2 \right) \frac{1}{W} \frac{\partial f}{\partial w} - w_{\parallel} \frac{\partial f}{\partial w_{\parallel}} \right] \\ = \langle \left(\frac{\partial f}{\partial t} \right)_c \rangle, \quad \text{where } w_{\perp}^2 = W^2 - w_{\parallel}^2. \end{aligned} \quad (16)$$

$$\text{and } E_{\parallel} = - \frac{\hat{b} \cdot \nabla P_{\parallel e}}{e n_e} + (P_{\perp e} - P_{\parallel e}) \frac{\nabla \cdot \hat{b}}{e n_e} \quad (18)$$

So there are the equations of KMHD.

When we come to the treatment of pressure-anisotropy-driven instabilities, we will ~~hopefully~~ conclude that these equations are in fact ill-posed in the sense that, unless the instabilities are stabilized, those equations will give rise to perturbations that grow the faster the greater is k — or require inclusion of non-gyroscopic FLR terms to be regularized at small scales.

(I'll derive some of those terms later on)

1.7 CGL Equations

↑
Chew-Goldberger-Low.

I promised evolution equations for p_{\perp} and p_{\parallel} , but so far have only delivered a kinetic equation for the gyrotrropic distribution function from which pressures can be calculated.

I am now going to make a further step by taking the $\frac{w_{\perp}^2}{2}$ and $w_{\perp} w_{\parallel}^2$ moments of eq. (16) and hence derive the desired eqns for p_{\perp} and p_{\parallel} . So, $\int d^3 \vec{w} m \frac{w_{\perp}^2}{2} (16)$:

$$\frac{dp_{\perp}}{dt} + \vec{b} \cdot \nabla \underbrace{\int d^3 \vec{w} m \frac{w_{\perp}^2}{2} w_{\parallel} f}_{\substack{\parallel \\ "parallel flux \\ of "free energy"}}, + (\nabla \cdot \vec{b}) \underbrace{\int d^3 \vec{w} m \frac{w_{\perp}^4}{4} \frac{\partial f}{\partial w_{\parallel}}}_{\substack{\parallel \\ "by parts"}}, + \left(\frac{e_s}{m_s} \vec{E}_{\parallel} - \vec{b} \cdot \frac{d\vec{u}}{dt} \right) \underbrace{\int d^3 \vec{w} m \frac{w^2 - w_{\parallel}^2}{2} \left(\frac{w_{\parallel}}{w} \frac{\partial f}{\partial w} + \frac{\partial f}{\partial w_{\parallel}} \right)}_{\substack{\parallel \\ "by parts"}}, = 2q_{\perp}$$

$$- (\nabla \cdot \vec{u}) \underbrace{\int d^3 \vec{w} m \frac{(w^2 - w_{\parallel}^2)^2}{2} \frac{\partial f}{\partial w^2}}, - \int d^3 \vec{w} m (w^2 - w_{\parallel}^2) f = -2p_{\perp}$$

$$+ (\vec{b} \cdot \nabla \vec{u}) \underbrace{\int d^3 \vec{w} m \frac{w^2 - w_{\parallel}^2}{2} \left[(w^2 - 3w_{\parallel}^2) \frac{\partial f}{\partial w^2} - w_{\parallel} \frac{\partial f}{\partial w_{\parallel}} \right]}, - \int d^3 \vec{w} m \left(\frac{w^2 - 3w_{\parallel}^2}{2} + \frac{w^2 - w_{\parallel}^2}{2} - \frac{w^2 - 3w_{\parallel}^2}{2} \right) f = -p_{\perp}$$

$$= \int d^3 \vec{w} m \frac{w_{\perp}^2}{2} \left\langle \left(\frac{\partial f}{\partial t} \right)_c \right\rangle \quad \left\{ \begin{array}{l} \text{this can be calculated} \\ \text{using a model Coll. operator} \end{array} \right\} = -\nu(p_{\perp} - p_{\parallel})$$

see Note on p. 22
e.g. Lorentz
 $\sqrt{\frac{2}{3}} \frac{1-\xi^2}{2} \frac{\partial f}{\partial \xi}$
 where $\xi = w_{\parallel}/w$

Assemble:

$$\begin{aligned} \frac{dp_{\perp}}{dt} &= -\vec{B} \cdot \nabla q_{\perp} - 2q_{\perp} \nabla \cdot \vec{B} - 2p_{\perp} \nabla \cdot \vec{u} + p_{\perp} \vec{B} \vec{B} : \nabla \vec{u} - \sqrt{(p_{\perp} - p_{\parallel})} \\ &= -\nabla \cdot (\vec{B} q_{\perp}) - q_{\perp} \nabla \cdot \vec{B} - \sqrt{(p_{\perp} - p_{\parallel})} \\ &\quad + p_{\perp} \underbrace{(\vec{B} \vec{B} : \nabla \vec{u} - \nabla \cdot \vec{u})}_{\left(\frac{1}{B} \frac{dB}{dt} \right)} - p_{\perp} \underbrace{\nabla \cdot \vec{u}}_{\left(-\frac{1}{n} \frac{dn}{dt} \right)} \end{aligned} \quad (19)$$

$$p_{\perp} \frac{d}{dt} \ln \frac{p_{\perp}}{nB} = -\nabla \cdot \vec{q}_{\perp} - q_{\perp} \nabla \cdot \vec{B} - \sqrt{(p_{\perp} - p_{\parallel})} \quad (20)$$

This is the more rigorous version of eq. (14), incorporating now the effects of compressibility and heat fluxes. It is worth noting the size of the heat flux terms:

$$\frac{q_{\perp}}{u p_{\perp}} \sim \frac{m v_{th}^3 \delta f / f}{u m v_{th}^2} \quad \begin{array}{l} \text{asymmetric part of the} \\ \text{distribution function,} \\ \text{usually small} \end{array} \sim \frac{v_{th}}{u} \frac{\delta f}{f}$$

This is small if flows are sonic $u \sim v_{th}$
("Bragiustkii ordering")

as order unity if $\frac{u}{v_{th}} \sim \frac{\delta f}{f} \ll 1$

("drift ordering", in the context of pressure anisotropies
these are called "Mikhailovskii terms")

- So pressure anisotropies are caused both by changes in n and B (\Leftarrow caused by flows)
- as by heat fluxes.

N.B.: obviously,
for electrons,
heat fluxes are
always important!

Let us complete the derivation and get p_{\parallel} :

$$\int d^3 \vec{w} m w_{\parallel}^2 \quad (16) :$$

$$\begin{aligned}
 & \frac{dp_{\parallel}}{dt} + \vec{B} \cdot \nabla \underbrace{\int d^3 \vec{w} m w_{\parallel}^3 f}_{\substack{\parallel \\ q_{\parallel} \\ \text{parallel flux} \\ \text{of "par. energy"} }} + (\nabla \cdot \vec{B}) \underbrace{\int d^3 \vec{w} m w_{\parallel}^2 \frac{w^2 - w_{\parallel}^2}{2} \frac{\partial f}{\partial w_{\parallel}}}_{\substack{\parallel \\ - \int d^3 \vec{w} m (w_{\parallel} w^2 - 2w_{\parallel}^3) f \\ = - \int d^3 \vec{w} m (w_{\perp}^2 w_{\parallel} - w_{\parallel}^3) f \\ = -2q_{\perp} + q_{\parallel} }} \\
 & + \left(\frac{e}{m_e} E_{\parallel} - \vec{B} \cdot \frac{d\vec{u}}{dt} \right) \underbrace{\int d^3 \vec{w} m w_{\parallel}^2 \left(2w_{\parallel} \frac{\partial f}{\partial w^2} + \frac{\partial f}{\partial w_{\parallel}} \right)}_{\substack{\parallel \\ 0}} \\
 & - (\nabla \cdot \vec{u}) \underbrace{\int d^3 \vec{w} m w_{\parallel}^2 (w^2 - w_{\parallel}^2) \frac{\partial f}{\partial w^2}}_{\substack{\parallel \\ - \int d^3 \vec{w} m w_{\parallel}^2 f = -p_{\parallel}}} + \\
 & + (\vec{B} \vec{B} : \nabla \vec{u}) \underbrace{\int d^3 \vec{w} m w_{\parallel}^2 \left[(w^2 - 3w_{\parallel}^2) \frac{\partial f}{\partial w^2} - w_{\parallel} \frac{\partial f}{\partial w_{\parallel}} \right]}_{\substack{\parallel \\ - \int d^3 \vec{w} m (w_{\parallel}^2 - 3w_{\parallel}^2) f = 2p_{\parallel}}} = \\
 & = \left\{ \int d^3 \vec{w} m w_{\parallel}^2 \left\langle \left(\frac{\partial f}{\partial t} \right)_c \right\rangle \right\} = -2\nu(p_{\parallel} - p_{\perp}) \quad \text{see Note}
 \end{aligned}$$

Note: Lorentz operator, the dipole model for collisions:

$$\left\langle \left(\frac{\partial f}{\partial t} \right)_c \right\rangle = \sqrt{\frac{\partial}{\partial \xi}} \frac{1-\xi^2}{2} \frac{\partial f}{\partial \xi} = \sqrt{\frac{\partial}{\partial w_{\parallel}}} \left(\frac{w^2 - w_{\parallel}^2}{2} \right) \frac{\partial f}{\partial w_{\parallel}}$$

$$\begin{aligned}
 \text{so } & \int d^3 \vec{w} m w_{\parallel}^2 \sqrt{\frac{\partial}{\partial w_{\parallel}}} \left(\frac{w^2 - w_{\parallel}^2}{2} \right) \frac{\partial f}{\partial w_{\parallel}} = -\sqrt{\int d^3 \vec{w} m w_{\parallel} (w^2 - w_{\parallel}^2) \frac{\partial f}{\partial w_{\parallel}}} = \\
 & = \sqrt{\int d^3 \vec{w} m (w^2 - 3w_{\parallel}^2) f} = 2\sqrt{(p_{\perp} - p_{\parallel})} \\
 & \int d^3 \vec{w} m \frac{w^2 - w_{\parallel}^2}{2} \sqrt{\frac{\partial}{\partial w_{\parallel}}} \frac{w^2 - w_{\parallel}^2}{2} \frac{\partial f}{\partial w_{\parallel}} = +\sqrt{\int d^3 \vec{w} m w_{\parallel} \frac{w^2 - w_{\parallel}^2}{2} \frac{\partial f}{\partial w_{\parallel}}} = -\sqrt{(p_{\perp} - p_{\parallel})}
 \end{aligned}$$

Assemble:

$$\begin{aligned}\frac{dp_{||}}{dt} &= -\vec{B} \cdot \nabla q_{||} - (\nabla \cdot \vec{B}) (q_{||} - 2q_{\perp}) - p_{||} (\nabla \cdot \vec{u}) - 2p_{||} \vec{B} \cdot \nabla \vec{u} - 2\nu(p_{||} - p_{\perp}) \\ &= -\nabla \cdot (\vec{B} q_{||}) + 2q_{\perp} \nabla \cdot \vec{B} - 2\nu(p_{||} - p_{\perp}) \\ &\quad - 2p_{||} \underbrace{(\vec{B} \cdot \nabla \vec{u} - \nabla \cdot \vec{u})}_{\left(\frac{1}{B} \frac{dB}{dt} \right)} - 3p_{||} \underbrace{\nabla \cdot \vec{u}}_{\left(-\frac{1}{n} \frac{dn}{dt} \right)}\end{aligned}\tag{21}$$

$$p_{||} \frac{d}{dt} \ln \frac{p_{||} B^2}{n^3} = -\nabla \cdot \vec{q}_{||} + 2q_{\perp} \nabla \cdot \vec{B} - 2\nu(p_{||} - p_{\perp})\tag{22}$$

this is to do with the so-called "second adiabatic invariant" or source invariant

Equations (20), (22) are known as CGL equations

— often in the version without the heat fluxes, in which case they are referred to as "double-adiabatic" equations (but that approximation tends to be very wrong because heat fluxes are not small, especially for electrons). If we must keep the heat fluxes, then obviously we still need the kinetic equation (16) to calculate them — this is the usual story with kinetic theory, moment equations do not close.

You might wonder why we bothered to derive these equations then. Well,

- 1) we learned some physics: what sets p_{\perp} and $p_{||}$
- 2) we have identified the key quantities that we might want to invent closures for: p_{\perp} , $p_{||}$, $q_{||}$, q_{\perp} .

Both pressure anisotropies and heat fluxes cause instabilities as one might take the view that instead of solving the kinetic eqn (which is ill posed anyway) we should set them to marginal values!

1.8 Pressure Anisotropy .

Since this is going to be the key quantity, let's work out what it is. Using eqs (19) and (21), we get

$$\begin{aligned} \frac{d}{dt}(p_{\perp} - p_{\parallel}) &= p_{\perp} \left(\frac{1}{B} \frac{dB}{dt} + \frac{1}{n} \frac{dn}{dt} \right) - \nabla \cdot \vec{q}_{\perp} - q_{\perp} \nabla \cdot \hat{b} - \nu(p_{\perp} - p_{\parallel}) \\ &\quad - \left\{ p_{\parallel} \left(-2 \frac{1}{B} \frac{dB}{dt} + 3 \frac{1}{n} \frac{dn}{dt} \right) - \nabla \cdot \vec{q}_{\parallel} + 2q_{\perp} \nabla \cdot \hat{b} - 2\nu(p_{\parallel} - p_{\perp}) \right\} \\ &= (p_{\perp} + 2p_{\parallel}) \frac{1}{B} \frac{dB}{dt} + (p_{\perp} - 3p_{\parallel}) \frac{1}{n} \frac{dn}{dt} - 3q_{\perp} \nabla \cdot \hat{b} - \nabla \cdot (\vec{q}_{\perp} - \vec{q}_{\parallel}) - 3\nu(p_{\perp} - p_{\parallel}) \end{aligned}$$

If we choose to express things in terms of total pressure (23)

$$p = \frac{2}{3} p_{\perp} + \frac{1}{3} p_{\parallel}, \text{ then } p_{\perp} = p + \frac{1}{3} (p_{\perp} - p_{\parallel})$$

$$p_{\parallel} = p - \frac{2}{3} (p_{\perp} - p_{\parallel})$$

Things simplify a bit when collisions are dominant, pressure anisotropy small & can be found by setting the rhs of (23) to 0 :

$$\boxed{\frac{p_{\perp} - p_{\parallel}}{p} \approx \frac{1}{\nu} \left[\frac{1}{B} \frac{dB}{dt} - \frac{2}{3} \frac{1}{n} \frac{dn}{dt} - \frac{\nabla \cdot (\vec{q}_{\perp} - \vec{q}_{\parallel}) + 3q_{\perp} \nabla \cdot \hat{b}}{3p} \right]} \quad (24)$$

Note. Under the same assumption of high collisionality,

$$q_{\perp} = \frac{1}{3} q_{\parallel} = -\frac{1}{2} n \frac{v_{th}^2}{\nu} \hat{b} \cdot \nabla T \quad \text{where } T = \frac{P}{n}$$

↑
this prefactor depends on the coll. operator used.

This follows from expanding around a Maxwellian equilibrium. [Note this again : when $\nu \gg \omega$, equations are closed :]
Braginskii theory

1.9 Heating

Finally, it is sometimes useful - and revealing - to know the equation for total energy

$$\int d^3\vec{w} \frac{m w^2}{2} f = p_{\perp} + \frac{1}{2} p_{\parallel} = \frac{3}{2} P = \frac{3}{2} n T$$

T by definition

Again using (19) or (21),

$$\underbrace{\frac{3}{2} \frac{d}{dt} n T}_{\parallel} = -\nabla \cdot (\vec{q}_{\perp} + \frac{1}{2} \vec{q}_{\parallel}) + (p_{\perp} - p_{\parallel}) \frac{1}{B} \frac{dB}{dt} + (p_{\perp} + \frac{3}{2} p_{\parallel}) \frac{1}{n} \frac{dn}{dt} \quad (25)$$

$$\frac{3}{2} n \frac{dT}{dt} + \frac{3}{2} p_{\perp} \frac{1}{n} \frac{dn}{dt} \quad \boxed{\frac{3}{2} n \frac{dT}{dt} = -\nabla \cdot \vec{q} + (p_{\perp} - p_{\parallel}) \frac{1}{B} \frac{dB}{dt} + p_{\parallel} \frac{1}{n} \frac{dn}{dt}} \quad (25)$$

Note that eqs. (23) and (26) can be used instead of (20), (22)

In a simple incompressible situation, the viscous heating term is explicitly positive:

$$(p_{\perp} - p_{\parallel}) \frac{1}{B} \frac{dB}{dt} = \frac{P}{\gamma} \left(\frac{1}{B} \frac{dB}{dt} \right)^2 = \frac{P}{\gamma} (\vec{b} \vec{b} : \nabla \vec{u})^2$$

Ex. Work out the total energy conservation law for

$$\mathcal{E} = \frac{m_i u^2}{2} + \frac{B^2}{8\pi} + \sum_s \frac{3}{2} n_s T_s \quad (27)$$

kinetic magnetic thermal