

## Magnetic pressure in a solenoid

A constant current intensity  $I$ , driven by an ideal current generator, flows in the coils of a cylindrical solenoid having radius  $a$ , length  $h \ll a$  and  $n$  coils per unit length. Boundary effects are negligible.

**a)** By directly computing the magnetic force on the coils show that on the surface of the solenoid there is a pressure  $P = B_0^2/2\mu_0$ , with  $B_0 = \mu_0 nI$  the inner field.

**b)** Now find the variation of the magnetic energy for a small increase  $\Delta a$  of the radius of the solenoid, and the corresponding work done by the current generator in order to keep  $I$  constant. Use the results to derive the pressure  $P$  again.

## Solution

a) The magnetic force on an infinitesimal segment of a circuit having length  $d\mathbf{l}$  is

$$d\mathbf{f} = I d\mathbf{l} \times \mathbf{B} . \quad (1)$$

Being  $\mathbf{B} = B\hat{\mathbf{z}}$ , the force  $d\mathbf{f}$  is perpendicular to the surface of the solenoid and directed outwards, i.e. the solenoid tends to expand radially. Since  $\mathbf{B}$  is discontinuous in the idealized limit of a surface current layer of infinitesimal thickness, we take as the value of  $\mathbf{B}$  on the surface the average  $B_0/2$  between the inner field  $B(r < a) = B_0$  and the outer field  $B(r > a) = 0$ , in the limit of infinite length  $a/h \rightarrow 0$ . Thus,  $d\mathbf{f} = IB_0 d\mathbf{l}/2$ . To find the force on a surface element of area  $dS = dhdl$  we notice that it contains  $ndh$  circuit segments, thus  $dF = (IB_0 dl/2)ndh = (nIB_0/2)dldh = (B_0^2/2\mu_0)dS$  from which we eventually obtain  $P = dF/dS = B_0^2/2\mu_0$ .

Alternatively, pursuing a more formal approach we may use  $\nabla \times \mathbf{B} = \mu_0 \mathbf{J}$  to write the force per unit volume as  $\mathbf{J} \times \mathbf{B} = -\hat{\mathbf{r}}(\partial_r B_z) B_z/\mu_0$ . Thus, by integrating over the thickness of the current layer

$$P = \int \mathbf{J} \times \mathbf{B} \cdot \hat{\mathbf{r}} dr = -\frac{1}{2\mu_0} \int_{a^-}^{a^+} \partial_r B_z^2 dr = \frac{B_0^2}{2\mu_0} . \quad (2)$$

b) The magnetic energy of the solenoid may be written using the “energy density” associated to the magnetic field,  $u_m = B^2/2\mu_0$ . Being  $B = B_0$  inside and  $B = 0$  out of the solenoid, we obtain  $U_m = (B_0^2/2\mu_0)\pi a^2 h$ . Thus, for a small variation of the radius  $\Delta a > 0$  the energy increases by  $\Delta U_m = (B_0^2/\mu_0)\pi h a \Delta a > 0$ .

The variation of  $a$  while keeping the current intensity  $I$  constant leads to a variation of the magnetic flux  $\Phi$  through the solenoid, thus an induced electromotive force  $\mathcal{E} = -d\Phi/dt$  appears. To keep  $I$  constant the generator must provide the power  $P = -\mathcal{E}I$ . The total work done is thus

$$W = \int P dt = I \int d\Phi = I \Delta\Phi , \quad (3)$$

where the total variation of the flux is  $\Delta\Phi = \Delta(B_0\pi a^2 nh) = 2\pi B_0 h n a \Delta a$ . In order to provide such work the internal energy of the generator decreases by  $\Delta U_g = -W = -2\pi n I B_0 h a \Delta a = -2\Delta U_m$ . Thus, the energy of the whole system (solenoid plus generator) varies by  $\Delta U_{\text{tot}} = \Delta U_g + \Delta U_m = -\Delta U_m < 0$ , so that  $-\Delta U_{\text{tot}}/\Delta a > 0$  confirming that the solenoid tends to expand radially driven by a pressure  $P = -(\Delta U_{\text{tot}}/\Delta a)/(2\pi a h) = B_0^2/2\mu_0$ .